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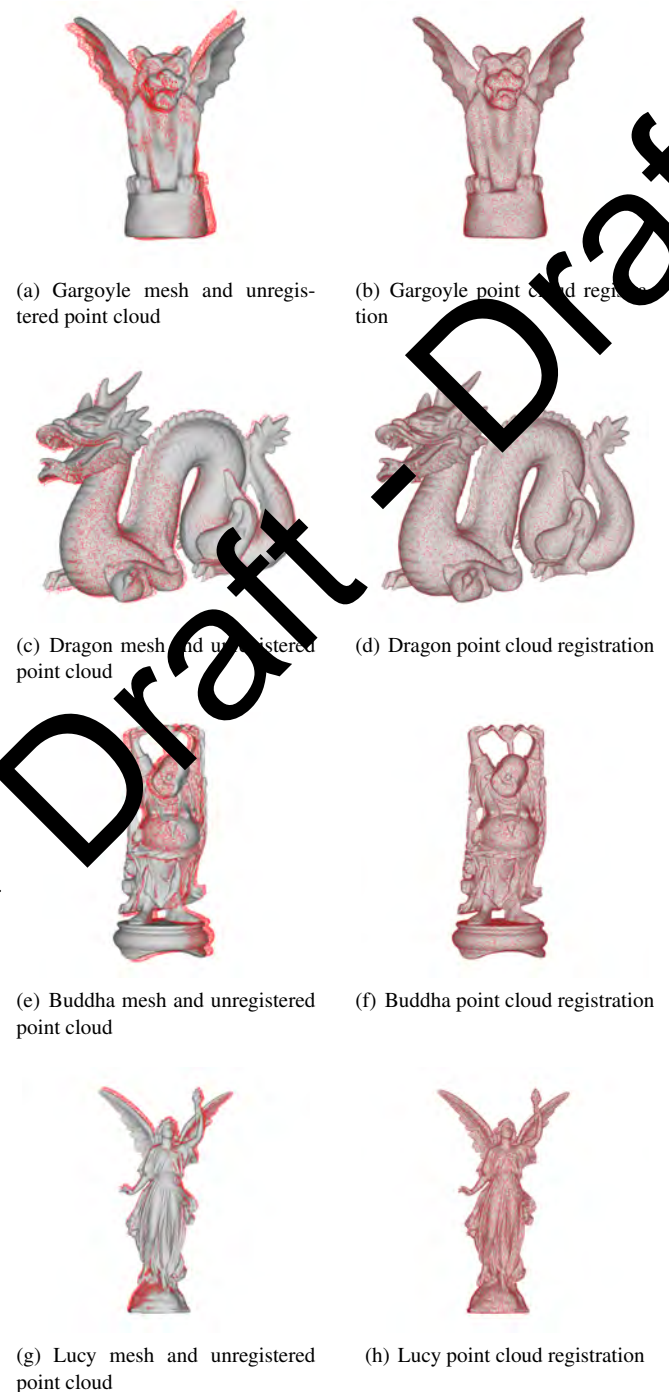


Figure 8: Point-cloud-to-mesh registration of 4 different models: Gargoyle, Dragon, Buddha and Lucy [CL96]. The registration algorithm minimizes the cloud-to-mesh distance.