

3 Erratum to “A novel technique for position analysis of planar  
4 compliant mechanisms” [[Mech. Machine Theory](#) 40 (2005)1224–1239]

5 S. Venanzi <sup>a</sup>, P. Giesen <sup>b</sup>, V. Parenti-Castelli <sup>a,\*</sup>

6 <sup>a</sup>DIEM – Department of Mechanical Engineering, University of Bologna, Viale Risorgimento 2, 40136 Bologna, Italy

7 <sup>b</sup>TNO – TPD, Institute of Applied Physics, DOI – Division Optical Instrumentation, Stieltjesweg 1, 2600 AD Delft, [The Netherlands](#)

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9 By kind information of the below cited authors of the present errata, the following two errors have been found:

- 10 (1) In Section 4, end of first paragraph, the correct external load compatible with the results reported in the case study is  
11  $F_R = (-0.3, 0.0)$  N instead of  $F_R = (-0.5, 0.0)$  N.  
12 (2) In [Section](#) 4.2, the correct expression for the angle  $\theta_3$  is  $\theta_3 = -(\gamma - \gamma_0 - \beta + \beta_0)$  instead of  $\theta_3 = \gamma - \gamma_0 - \beta + \beta_0$ .

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14 The authors of the original paper thank the commentators for their detailed analysis and for kindly conveying this infor-  
15 mation both to them and to the readers of this journal.

16 Authors of the errata:

17 Jorge E. Correa, Oscar E. Ruiz, Sebastián Durango

18 Laboratory of CAD CAM CAE, EAFIT University, Cra. 49 [No.](#) 7-sur-50, Medellín, [Colombia](#).

19 Tel.: +57 4 261 9500x9521, 9382.

20 E-mail addresses: [jcorre20@eafit.edu.co](mailto:jcorre20@eafit.edu.co); [oruiz@eafit.edu.co](mailto:oruiz@eafit.edu.co); [sdurang1@eafit.edu.co](mailto:sdurang1@eafit.edu.co)